

# Kinetic Models for Magnetized Plasmas

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Introducing the magnetized Vlasov–Poisson system

The Bernstein–Landau paradox

Propagation of velocity moments and uniqueness for the magnetized Vlasov–Poisson system

# Outline

Introducing the magnetized Vlasov–Poisson system

The Bernstein–Landau paradox

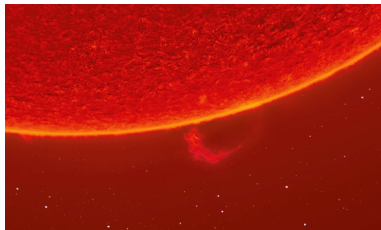
Propagation of velocity moments and uniqueness for the magnetized Vlasov–Poisson system

# Plasmas

## Definition (Plasma)

Plasma is a state of matter, characterized by an important ionization of particles.

- Term "plasma" first used by Irving Langmuir <sup>1</sup> to describe an ionized gas.
- Plasma represents more than 99% of ordinary matter in the universe.



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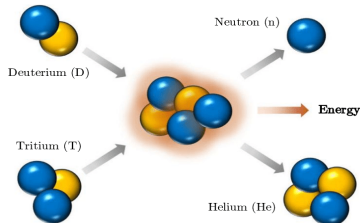
<sup>1</sup>I. Langmuir, Oscillations in Ionized Gases, Proceedings of the National Academy of Science, 14:627–637, 1928.

# Nuclear fusion

## Definition (Nuclear fusion)

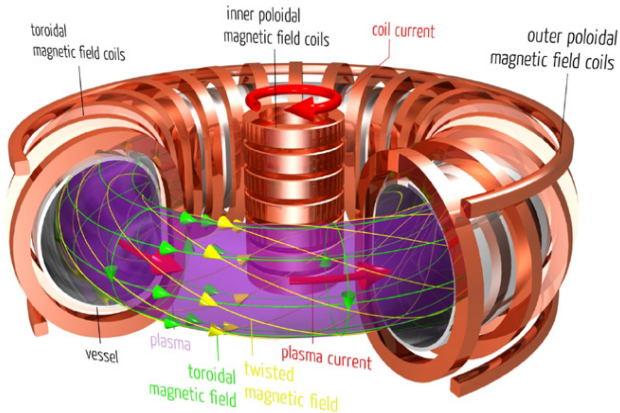
Combination of two atomic nuclei to form one atomic nuclei.

- Fusion of light nuclei releases enormous amounts of energy.
- This reaction takes place in plasmas under certain conditions: very high temperature and high enough particle density.
- One approach to harness nuclear fusion of light nuclei is via magnetic confinement.



# Magnetic confinement fusion

- Use an intense external (not self-induced) magnetic field  $B$  to confine the hot plasma.
- Feasibility of controlled nuclear fusion: ITER tokamak under construction in Cadarache (south of France).



## Kinetic formalism and the Vlasov equation

Trajectory  $(X(t), V(t))$  of one particle of mass  $m$  subject to a force  $F(t)$  given by:

$$\begin{cases} \dot{X}(t) = V(t), \\ \dot{V}(t) = \frac{1}{m}F(t). \end{cases} \quad (1)$$

Large number of identical particles allows for a kinetic description of the system.  $f(t, x, v)$  is the number density of particles which are located at the position  $x$  and have velocity  $v$  at time  $t$  and satisfies:

$$\partial_t f(t, x, v) + v \cdot \nabla_x f(t, x, v) + \frac{1}{m} F(t) \cdot \nabla_v f(t, x, v) = 0 \quad (2)$$

with  $(t, x, v) \in \mathbb{R}^+ \times X^3 \times \mathbb{R}^3$ ,  $X = \mathbb{R}$  or  $X = \mathbb{T}$ .

# The magnetized Vlasov–Poisson system for electrons

- At the time scale of electrons: ions are static  $\implies f_{ion}$  is constant.
- At the time scale of ions: electrons are at thermal equilibrium  $\implies f_{electron} = \text{Maxwell–Boltzmann type distribution}$ .

At the time scale of electrons, we have:

$$\begin{cases} \partial_t f + \mathbf{v} \cdot \nabla_x f + \frac{q_e}{m_e} (\mathbf{E} + \mathbf{v} \wedge \mathbf{B}) \cdot \nabla_v f = 0, \\ \operatorname{div}_x \mathbf{E}(t, \mathbf{x}) = \frac{q_{ion}}{\epsilon_0} \int_{\mathbb{R}^3} f_{ion}(\mathbf{x}, \mathbf{v}) d\mathbf{x} d\mathbf{v} + \frac{q_e}{\epsilon_0} \int_{\mathbb{R}^3} f(t, \mathbf{x}, \mathbf{v}) d\mathbf{x} d\mathbf{v}, \end{cases} \quad (3)$$

with  $f \equiv f(t, \mathbf{x}, \mathbf{v})$  the distribution function of electrons,  $f_{ion}(\mathbf{x}, \mathbf{v})$  the constant ion distribution,  $\mathbf{E} \equiv \mathbf{E}(t, \mathbf{x})$  the self-consistent electric field and  $\mathbf{B} \equiv \mathbf{B}(t, \mathbf{x})$  the **given** external magnetic field.



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## Landau damping

Exponential decrease in time of longitudinal waves in plasma.

- First predicted by Landau with the linearized Vlasov–Poisson system where he showed damping of the electric field  $E$ .<sup>2</sup>

$$\begin{cases} \partial_t f + v \cdot \nabla_x f + \frac{q}{m} E \cdot \nabla_v f_0 = 0, \\ \partial_x E = \frac{q}{\epsilon_0} \int f dv_1 dv_2, \end{cases} \quad (4)$$

with  $f = f(t, x, v)$ ,  $(t, x, v) \in \mathbb{R}_+ \times \mathbb{T}^3 \times \mathbb{R}^3$  the distribution of electrons and  $f_0 = e^{-\frac{|v|^2}{2}}$  the equilibrium Maxwellian distribution.

- Using the Fourier–Laplace transform, Landau showed the damping of the electric field

$$|E_k(t)| \leq C e^{-\alpha_k t}. \quad (5)$$

- Irreversible behavior observed in a reversible in time system.
- Recently extended to the nonlinear setting by Mouhot and Villani <sup>3</sup>.

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<sup>2</sup>L. Landau, On the vibration of the electronic plasma, J. Phys. USSR, 1946.

<sup>3</sup>C. Mouhot and C. Villani, On Landau damping, Acta Math., 2011.

# The paradox

## The Bernstein-Landau paradox

”In unmagnetized plasmas, waves exhibit Landau Damping, while in magnetized plasmas, waves perpendicular to the magnetic field are exactly undamped, independently of the strength of the magnetic field”.

- Magnetized plasmas first studied by Bernstein <sup>4</sup>.
- Other physical works <sup>5</sup> have highlighted a discontinuity between the theory of unmagnetized plasmas and the theory of magnetized plasmas, thus speaking of a paradox.
- Very few mathematical papers, recently studied in <sup>6</sup> using Fourier–Laplace in a 3d-3v setting.

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<sup>4</sup>I. Bernstein, Waves in a Plasma in a Magnetic Field, Phy. Review, 1958.

<sup>5</sup>A. I. Sukhorukov and P. Stubbe, On the Bernstein-Landau paradox, Phy. of Plasmas, 1997.

<sup>6</sup>J. Bedrossian and F. Wang, The linearized Vlasov and Vlasov-Fokker-Planck equations in a uniform magnetic field, J. Stat. Phys., 2020.

# Numerical illustration of the influence of $B$ : magnetic recurrence

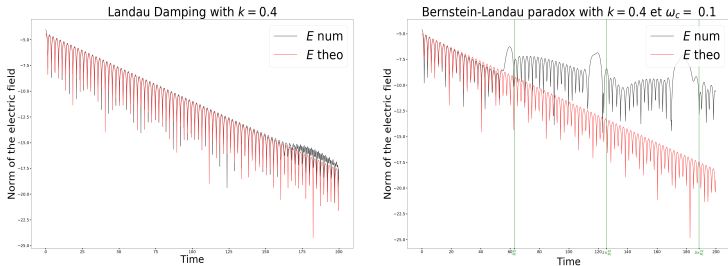


Figure: Damped and undamped electric field

This is a magnetic recurrence <sup>7</sup>.

<sup>7</sup>Not a numerical recurrence *Recurrence phenomenon for Vlasov-Poisson simulations on regular finite element mesh*, M. Mehrenberger, L. Navoret, N. Pham, Commun. Comput. Phys., 2020.

# The 1d-2v framework

## The 1d-2v magnetized Vlasov-Poisson system

$$\begin{cases} \partial_t f + v_1 \partial_x f - E \partial_{v_1} f + \underbrace{\omega (-v_2 \partial_{v_1} + v_1 \partial_{v_2})}_{=-v \wedge B} f = 0, \\ \partial_x E = 2\pi - \int f dv_1 dv_2. \end{cases} \quad (6)$$

- The unknowns are the density of electrons  $f(t, x, v_1, v_2) \geq 0$  and the electric field  $E(t, x)$ .
- The domain is  $\Omega = \mathbb{T} \times \mathbb{R}^2$ ,  $\mathbb{T} = [0, 2\pi]_{\text{per}}$  is the 1D-torus.
- Here  $\omega > 0$  is the constant cyclotron frequency for electrons ( $B = (0, 0, \omega)$ ).
- $\frac{q_e}{m_e}$  normalized to  $-1$ .
- Ions are considered as a motionless background of neutralizing positive charge.

## Linearized system

We linearize (6) by writing

$$f = f_0 + \varepsilon \sqrt{f_0} u + O(\varepsilon^2) \text{ and } E = \varepsilon F + O(\varepsilon^2).$$

where  $(f_0, E_0) = (\exp(-\frac{v_1^2 + v_2^2}{2}), 0)$  is a stationary solution of (6).

### Linearized Vlasov–Poisson with magnetic field

$$\begin{cases} \partial_t u + v_1 \partial_x u + F v_1 e^{-\frac{v_1^2 + v_2^2}{4}} + \omega (-v_2 \partial_{v_1} + v_1 \partial_{v_2}) u = 0, \\ \partial_x F = - \int u e^{-\frac{v_1^2 + v_2^2}{4}} dv_1 dv_2. \end{cases} \quad (7)$$

- $\int u e^{-\frac{v_1^2 + v_2^2}{4}} dx dv_1 dv_2 = 0$ . (total mass equal zero)
- $\int F dx = 0$ . ( $F$  is derived from a potential)

## Reformulation with the Ampère equation

We can rewrite the system with the Ampère equation because both systems are equivalent.

### The linear 1d-2v Vlasov–Ampère system

$$\begin{cases} \partial_t u + v_1 \partial_x u + F v_1 e^{-\frac{v_1^2 + v_2^2}{4}} + \omega(-v_2 \partial_{v_1} + v_1 \partial_{v_2}) u = 0, \\ \partial_t \mathbf{F} = \mathbf{1}^* \int \mathbf{u} e^{-\frac{v_1^2 + v_2^2}{4}} \mathbf{v}_1 d\mathbf{v}_1 d\mathbf{v}_2. \end{cases} \quad (8)$$

$$\text{with } \mathbf{1}^* g(x) = g(x) - \frac{1}{2\pi} \int_{\mathbb{T}} g(x) dx.$$

# A self-adjoint Vlasov–Ampère operator

## Final formulation

$$\partial_t \begin{pmatrix} u \\ F \end{pmatrix} = iH \begin{pmatrix} u \\ F \end{pmatrix}, H = i \left( \begin{array}{c|c} \underbrace{v_1 \partial_x + \omega(v_2 \partial_{v_1} - v_1 \partial_{v_2})}_{:= H_0} & v_1 e^{-\frac{v_1^2 + v_2^2}{4}} \\ \hline -1^* \int v_1 e^{-\frac{v_1^2 + v_2^2}{4}} \cdot dv_1 dv_2 & 0 \end{array} \right).$$

$$\mathcal{H} = \underbrace{(L^2(\mathbb{T} \times \mathbb{R}^2) \cap \left\{ \int u \sqrt{f_0} dx dv_1 dv_2 = 0 \right\})}_{=L_0^2(\mathbb{T} \times \mathbb{R}^2)} \times \underbrace{(L^2(\mathbb{T}) \cap \left\{ \int F dx = 0 \right\})}_{=L_0^2(\mathbb{T})}$$

and  $H$  a **self-adjoint** operator with domain  $D(H) := D(H_0) \times L_0^2(\mathbb{T})$ .



# Spectral properties of Vlasov equations

- For a general self-adjoint operator  $H$  with an ambient Hilbert space  $\mathcal{H}$ : then we have the following decomposition of  $\mathcal{H}$  in terms of the spectrum of  $H$ :  $\mathcal{H} = \mathcal{H}_H^{ac} \oplus \mathcal{H}_H^{sc} \oplus \mathcal{H}_H^{pp}$ .<sup>8 9</sup>
- Spectrum of the Vlasov–Ampère operator with  $\omega = 0$  studied in<sup>10</sup>  
<sup>11</sup>: the operator has only absolutely continuous spectrum and a kernel (as expected)  $\mathcal{H} = \ker H \oplus \mathcal{H}_H^{ac}$ .

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<sup>8</sup>T. Kato, Perturbation theory for linear operators, 1966.

<sup>9</sup>D.R. Yafaev, Scattering theory: Some old and new problems, 2000.

<sup>10</sup>B. Després, Symmetrization of Vlasov–Poisson Equations, SIAM J. Math. Anal., 2014.

<sup>11</sup>B. Després, Trace class properties of the linear Vlasov–Poisson equation, J. of Spectral Theory, 2021.

# Discrete spectrum for the Vlasov–Ampère operator

Theorem (Charles, Després, R., Weder <sup>12</sup>)

*We have completeness of the eigenspaces:*

$$\mathcal{H} = \mathcal{H}_H^{PP},$$

*and the eigenvalues of  $H$  are  $0$ ,  $m\omega$  and  $\lambda_m$ ,  $m \neq 0$ .*

Two different proofs:

- Direct computations.
- Weyl theorem on the invariance of the essential spectrum.

Explanation for the Bernstein–Landau paradox

The magnetic term  $(v \wedge B) \cdot \nabla_v f$  can be seen as a perturbation that modifies the domain of the Vlasov–Ampère operator.

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<sup>12</sup>F. Charles, B. Després, A. Rege and R. Weder, The magnetized Vlasov–Ampère system and the Bernstein–Landau paradox, J. Stat. Phys., 2021.

## Numerical illustration: initialization

**Objective:** compare the numerical and theoretical solutions of Vlasov–Ampère when initializing with an eigenvector.

- We consider an eigenvector  $(w_{n,m}, F_n)$  associated to the Fourier mode  $n \neq 0$  and the eigenvalue  $\lambda_m$ , so the solution  $(u, F)$  is given by

$$(u, F)(t) = e^{i\lambda_m t} (w_{n,m}, F_n).$$

- $w_{n,m}$  and  $F_n$  are given by

$$w_{n,m} = e^{in(x - \frac{v_2}{\omega}t)} e^{-\frac{t^2}{4}} \sum_{p \in \mathbb{Z}^*} \frac{p\omega}{p\omega + \lambda_m} e^{pi\varphi} J_p \left( \frac{nr}{\omega} \right) \text{ and } F_n = -ine^{inx}.$$

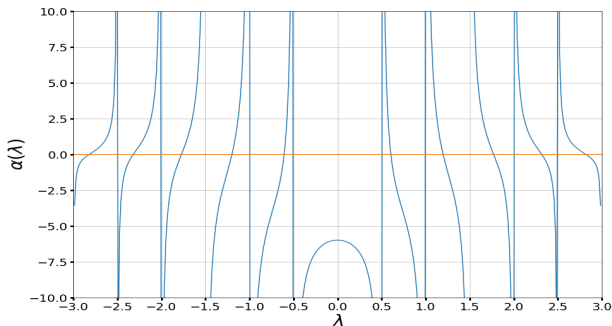
- $\lambda_m$  is one of the roots of a secular equation given by:

$$\alpha(\lambda) = -1 - \frac{2\pi}{n^2} \sum_{m \in \mathbb{Z}^*} \frac{m\omega}{m\omega + \lambda} \int_0^\infty e^{-\frac{r^2}{2}} J_m \left( \frac{nr}{\omega} \right)^2 r dr = 0.$$

## Numerical illustration: secular equation

$\alpha$  has a unique root in

- $]m\omega, (m+1)\omega[$  for  $m \geq 1$ ,
- $](m-1)\omega, m\omega[$  for  $m \leq -1$ .



For  $(n, m) = (1, 2)$ , we compute  $\lambda_2 \approx 1.19928$ .

## Numerical illustration: results

Simulations with a classical "backward" semi-lagrangian scheme,  
 $N_x = 33$ ,  $N_{v_1} = N_{v_2} = 63$ ,  $L_x = 2\pi$ ,  $L_{v_1} = L_{v_2} = 10$ ,  $\omega = 0.5$ ,  $n = 1$ , and  
 $T_f = \frac{\pi}{2\lambda_m}$ .

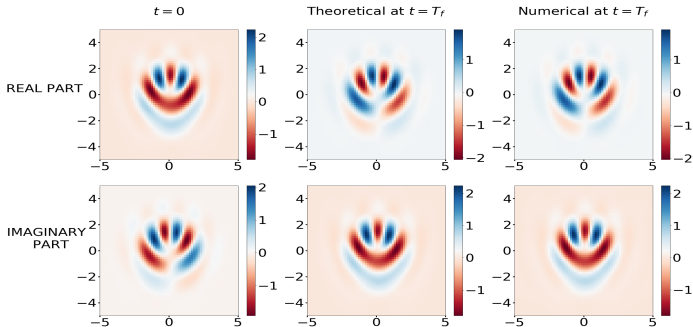


Figure: Real and imaginary parts of  $u$  in  $V_1$ - $V_2$  plane for  $x = 0$ .

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## Back to the nonlinear system in $\mathbb{R}^3 \times \mathbb{R}^3$

$$\begin{cases} \partial_t f + v \cdot \nabla_x f + (E + v \wedge B) \cdot \nabla_v f = 0, \\ E(t, x) = \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \frac{x-y}{|x-y|} f(t, y, v) dv dy. \end{cases} \quad (\text{VPwB})$$

Energy of the system and macroscopic density  $\rho$

$$\mathcal{E}(t) := \frac{1}{2} \iint_{\mathbb{R}^3 \times \mathbb{R}^3} |v|^2 f(t, x, v) dx dv + \frac{1}{2} \int_{\mathbb{R}^3} |E(t, x)|^2 dx,$$

$$\rho(t, x) := \int_{\mathbb{R}^3} f(t, x, v) dv.$$

### Results on existence of solutions in the unmagnetized case:

- Existence of weak solutions [Arsenev, 1975]
- Small initial data [Bardos, Degond, 1985]
- Existence of smooth solutions [Pfaffelmoser, 1992]
- **Propagation of velocity moments** [Lions, Perthame, 1991]

We will first consider a constant  $B$

$$B = \begin{pmatrix} 0 \\ 0 \\ \omega \end{pmatrix}.$$

## Differential inequality on $M_k$

Let  $k \geq 0$ , the velocity moment of order  $k$  is defined by

$$M_k(t) := \iint_{\mathbb{R}^3 \times \mathbb{R}^3} |v|^k f(t, x, v) dv dx.$$

Propagation of velocity moments:

$$\iint_{\mathbb{R}^3 \times \mathbb{R}^3} |v|^k f^{in}(x, v) dv dx < \infty \implies \iint_{\mathbb{R}^3 \times \mathbb{R}^3} |v|^k f(t, x, v) dv dx < \infty$$

$$\begin{aligned} \left| \frac{d}{dt} M_k(t) \right| &= \left| \iint |v|^k (-v \cdot \nabla_x f - (E + v \wedge B) \cdot \nabla_v f) dv dx \right|, \\ &= \left| \iint |v|^k \operatorname{div}_v ((E + v \wedge B) f) dv dx \right|, \\ &= \left| \iint k |v|^{k-2} v \cdot (E + v \wedge B) f dv dx \right|, \\ &\leq C \|E(t)\|_{k+3} M_k(t)^{\frac{k+2}{k+3}}. \end{aligned}$$

Next step: we need to control of  $\|E(t)\|_{k+3}$  with  $M_k(t)^\alpha$  with  $\alpha \leq \frac{1}{k+3}$ .



A representation formula for  $\rho$ 

$$\partial_t f + v \cdot \nabla_x f + (v \wedge B) \cdot \nabla_v f = -E \cdot \nabla_v f$$

$$\begin{cases} \frac{d}{ds} (X(s), V(s)) = (V(s), V(s) \wedge B) = (V(s), (\omega V_2(s), -\omega V_1(s), 0)), \\ (X(t), V(t)) = (x, v), \end{cases}$$

$$\begin{cases} V(s) = \begin{pmatrix} v_1 \cos(\omega(s-t)) + v_2 \sin(\omega(s-t)) \\ -v_1 \sin(\omega(s-t)) + v_2 \cos(\omega(s-t)) \\ v_3 \end{pmatrix}, \\ X(s) = \begin{pmatrix} x_1 + \frac{v_1}{\omega} \sin(\omega(s-t)) + \frac{v_2}{\omega} (1 - \cos(\omega(s-t))) \\ x_2 + \frac{v_1}{\omega} (\cos(\omega(s-t)) - 1) + \frac{v_2}{\omega} \sin(\omega(s-t)) \\ x_3 + v_3(s-t) \end{pmatrix}, \end{cases} \quad (9)$$

$$\rho(t, x) = \underbrace{\int_v f^{in}(X(0), V(0)) dv}_{=:\rho_0(t, x)} + \operatorname{div}_x \underbrace{\int_0^t \int_v (fH_t)(s, X(s), V(s)) dv ds}_{=:\sigma(s, t, x)}.$$

## Singularities at multiples of the cyclotron period

$$\begin{aligned} E(t, x) &= - \left( \nabla \frac{1}{|\cdot|} \star \rho \right) (t, x) = E^0(t, x) + \tilde{E}(t, x), \\ \|E(t)\|_{k+3} &\leq \|E^0(t)\|_{k+3} + \int_0^t \|\sigma(s, t, x)\|_{k+3} ds, \\ \|\sigma(s, t, \cdot)\|_{k+3} &\leq C \frac{\sqrt{2}}{s} \left( \frac{\omega^2 s^2}{2(1 - \cos(\omega s))} \right)^{\frac{3}{2}} M_k(t - s)^{\frac{1}{k+3}}. \end{aligned} \quad (10)$$

### Proposition (Propagation of moments on a finite interval)

For all  $0 \leq t \leq T_\omega := \frac{\pi}{\omega}$  we have

$$\iint_{\mathbb{R}^3 \times \mathbb{R}^3} |v|^k f(t, x, v) dx dv \leq C < +\infty,$$

with  $C = C(k, \omega, \|f^{in}\|_1, \|f^{in}\|_\infty, \mathcal{E}_{in}, M_k(f^{in}))$ .

## Propagation of moments for all time

We have that

- $\|f^{in}\|_1 = \|f(T_\omega)\|_1$  and  $\|f^{in}\|_\infty = \|f(T_\omega)\|_\infty$ ,
- $\mathcal{E}(T_\omega) \leq \mathcal{E}_{in}$ ,
- $M_k(f(T_\omega)) \leq C(k, \omega, \|f^{in}\|_1, \|f^{in}\|_\infty, \mathcal{E}_{in}, M_k(f^{in}))$ .

This means  $f(T_\omega)$  verifies the same assumptions as  $f^{in} \implies$  we can show propagation of moments for all time by induction.

### Additional results

- Propagation of the regularity of  $f^{in}$ .
- Uniqueness if  $\rho \in L^\infty([0, T] \times \mathbb{R}^3)$ <sup>13</sup>.

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<sup>13</sup>G. Loeper, Uniqueness of the solution to the Vlasov–Poisson system with bounded density, 2006.

## Propagation of velocity moments for (VPwB)

### Theorem (R. <sup>14</sup>)

Let  $k_0 > 3$ ,  $T > 0$ ,  $f^{in} = f^{in}(x, v) \geq 0$  a.e. with  $f^{in} \in L^1 \cap L^\infty(\mathbb{R}^3 \times \mathbb{R}^3)$  and assume that

$$\iint_{\mathbb{R}^3 \times \mathbb{R}^3} |v|^{k_0} f^{in} dx dv < \infty. \quad (11)$$

Then there exists  $C > 0$  and a weak solution  $f$  to (VPwB) with  $B = (0, 0, \omega)$  such that

$$\iint_{\mathbb{R}^3 \times \mathbb{R}^3} |v|^{k_0} f(t, x, v) dx dv \leq C < +\infty, \quad 0 \leq t \leq T \quad (12)$$

with  $C$  that depends on

$$T, k_0, \omega, \mathcal{E}_{in}, \|f^{in}\|_1, \|f^{in}\|_\infty, \mathcal{E}_{in}, M_k(f^{in}). \quad (13)$$

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<sup>14</sup>A. Rege, The Vlasov–Poisson system with a uniform magnetic field: propagation of moments and regularity, SIAM J. Math. Anal., 2021.

## Uniqueness in the unmagnetized case

### Theorem (Miot <sup>15</sup>)

Let  $T > 0$ . Then there exists at most one solution  $f \in L^\infty([0, T], L^1 \cap L^\infty(\mathbb{R}^3 \times \mathbb{R}^3))$  to Vlasov–Poisson such that

$$\sup_{[0, T]} \sup_{p \geq 1} \frac{\|\rho(t)\|_p}{p} < +\infty. \quad (14)$$

New uniqueness criterion which allows for solutions with unbounded  $\rho$ .

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<sup>15</sup>E. Miot., A uniqueness criterion for unbounded solutions to the Vlasov–Poisson system, Comm. Math. Phys., 2016.

## Characteristics

Now we have  $B := B(t, x)$  such that

$$B \in W^{1,\infty}(\mathbb{R}_+ \times \mathbb{R}^3). \quad (15)$$

$$\begin{cases} \frac{d}{ds} X(s; t, x, v) = V(s; t, x, v), \\ \frac{d}{ds} V(s; t, x, v) = E(s, X(s; t, x, v)) + V(s; t, x, v) \wedge B(s, X(s; t, x, v)). \end{cases}$$

Consider two solutions  $f_1, f_2$  with  $(X_1, V_1), (X_2, V_2)$  the corresponding characteristics. We study the distance

$$D(t) = \iint_{\mathbb{R}^3 \times \mathbb{R}^3} |X_1(t, x, v) - X_2(t, x, v)| f^{in}(x, v) dx dv. \quad (16)$$

## Additional terms in the magnetized case

$$\begin{aligned}
 D(t) &\leq \int_0^t \int_0^s \int_{\mathbb{R}^6} |E_1(\tau, X_1(\tau)) - E_2(\tau, X_2(\tau))| \\
 &\quad + |V_1(\tau) \wedge B(\tau, X_1(\tau)) - V_2(\tau) \wedge B(\tau, X_2(\tau))| f^{in}(x, v) dx dv d\tau ds, \\
 &\leq \int_0^t \int_0^s \int_{\mathbb{R}^6} |E_1(\tau, X_1(\tau)) - E_2(\tau, X_2(\tau))| f^{in}(x, v) dx dv d\tau ds \\
 &\quad + \|B\|_\infty \int_0^t \int_0^s \int_{\mathbb{R}^6} |V_1(\tau) - V_2(\tau)| f^{in}(x, v) dx dv d\tau ds \\
 &\quad + \int_0^t \int_0^s \int_{\mathbb{R}^6} |V_2(\tau)| |B(\tau, X_1(\tau)) - B(\tau, X_2(\tau))| f^{in}(x, v) dx dv d\tau ds, \\
 &= I(t) + J(t) + K(t).
 \end{aligned}$$

The additional terms  $J(t)$ ,  $K(t)$  are controlled with  $\|\rho_1\|_p$ ,  $\|\rho_2\|_p$  and velocity moments of  $f^{in}$ .

# Uniqueness criterion with a general magnetic field

## Theorem (R.)

Let  $T > 0$  and  $B := B(t, x)$  such that  $B \in W^{1, \infty}(\mathbb{R}_+ \times \mathbb{R}^3)$ .  
If  $f^{in}$  satisfies

$$\forall k \geq 1, \quad \iint_{\mathbb{R}^3 \times \mathbb{R}^3} |v|^k f^{in}(x, v) dx dv \leq (C_0 k)^{\frac{k}{3}},^{16} \quad (17)$$

with  $C_0$  a constant independent of  $k$ , then there exists at most one solution  $f \in L^\infty([0, T], L^1 \cap L^\infty(\mathbb{R}^3 \times \mathbb{R}^3))$  to the Cauchy problem for the magnetized Vlasov–Poisson system. If such a solution exists then it will verify

$$\sup_{[0, T]} \sup_{p \geq 1} \frac{\|\rho(t)\|_p}{p} < +\infty. \quad (18)$$

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<sup>16</sup>E. Miot, A uniqueness criterion for unbounded solutions to the Vlasov–Poisson system, Comm. Math. Phys., 2016.



## Propagation of moments with a general magnetic field

$$Q(t) := \sup \left\{ \int_0^t |E(s, X(s; 0, x, v))| ds, (x, v) \in \mathbb{R}^3 \times \mathbb{R}^3 \right\}, \quad (19)$$

$$N_T := \sup_{0 \leq t \leq T} Q(t) \leq C, \quad (20)$$

$$\begin{aligned} M_k(t) &= \iint_{\mathbb{R}^3 \times \mathbb{R}^3} |V(t; 0, x, v)|^k f^{in}(x, v) dv dx, \\ &\leq \iint_{\mathbb{R}^3 \times \mathbb{R}^3} (|v| + N_T)^k \exp(kt \|B\|_\infty) f^{in}(x, v) dv dx. \end{aligned}$$

In the unmagnetized case we have:

**Theorem (Pallard <sup>17</sup>)**

Let  $T > 0$ , then for all  $0 \leq t \leq T$ ,

$$Q(t) \leq C(T^{\frac{1}{2}} + T^{\frac{7}{5}}). \quad (21)$$

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<sup>17</sup>C. Pallard, Moment propagation for weak solutions to the Vlasov-Poisson system, Comm. Partial Differential Equations, 2012.

## Estimates on the characteristics

### Conjecture

For all time  $t$  such that  $0 \leq t \leq T_B$ ,

$$Q(t) \leq C \exp(T_B \|B\|_\infty)^{\frac{2}{5}} (T_B^{\frac{1}{2}} + T_B^{\frac{7}{5}}). \quad (22)$$

- The conjecture is true if we assume  $B := B(t)$  independent of  $x$ .
- Difficulty when  $B := B(t, x)$ : control of the difference between velocity characteristics  $|V(s) - V_*(s)|$  in terms of  $Q(t)$  and  $|V(s) - V_*(s)|$ :

$$\begin{aligned} |V(s) - V_*(s)| &\leq |v - v_*| + 2Q(t) \\ &\quad + \int_s^t |V(s) \wedge B(s, X(s)) - V_*(s) \wedge B(s, X_*(s))| ds. \end{aligned}$$

Thank you for your attention!