Aspects of Signatures

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We consider differential equations of the form

$$dY_t = \sum_i V_i(Y_t) du_t^i, \ Y_0 = y \in E$$

to construction evolutions in state space E (could be a manifold of finite or infinite dimension) depending on local characteristics, initial value $y \in E$ and the control u.

If the map $y \to Y_T$ is considered CODEs are an exciting model for feedforward neural networks, residual networks, etc (see joint work with Christa Cuchiero and Martin Larsson).

For this talk we fix $y \in E$ and consider

 $u \mapsto W \operatorname{Evol}_{s,t}(y)$

and train the readout and/or the vector fields.

Does this also correspond to classes of networks? Yes: these are continuous time versions of rNNs, LSTMs, etc.

It can be used for time series, predictions, etc.

... We aim to learn an input-output map on a high- or infinite dimensional input state space. Consider the input as well as the output dynamic, e.g. a time series. An example: learn a given evolution on state space E:

Paradigm of Reservoir computing (Herbert Jäger, Lyudmila, Grigoryeva, Wolfgang Maas, Juan-Pablo Ortega, et al.)

Split the input-output map into a generic part of generalized rNN-type (the *reservoir*), which is *not* trained and a readout part, which is trained.

Often the readout is chosen linear and the reservoir has random features. The reservoir is usually a numerically very tractable dynamical system.

Applications of RC

- Often reservoirs can be realized physically, whence ultrafast evaluations are possible. Only the readout map *W* has to be trained.
- One can learn dynamic phenomena *without* knowing the specific characteristics.
- It works unreasonably well with generalization tasks.

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An instance of RC are CODEs/RDEs/SDEs

Consider a controlled differential equation

$$dY_t = \sum_{i=1}^d V_i(Y_t) du_t^i, \ Y_0 = y \in E$$

for some smooth vector fields $V_i : E \to TE$, i = 1, ..., d and d independent (Stratonovich) Brownian motions u^i , or finite variation continuous controls, or a rough path, or a semi-martingale. This describes a controlled dynamics on E.

We want to learn the dynamics, i.e. the map

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(input control u) \mapsto (solution Y).
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Obviously a complicated, non-linear map, ...

We introduce some notation for this purpose:

Definition

Let $V: E \to E$ be a smooth vector field, and let $f: E \to \mathbb{R}$ be a smooth function, then we call

$$Vf(x) = df(x) \bullet V(x)$$

the transport operator associated to V, which maps smooth functions to smooth functions and determines V uniquely.

Taylor expansion

Theorem

Let Evol be a smooth evolution operator on a convenient manifold E which satisfies (again the time derivative is taken with respect to the forward variable t) a controlled ordinary differential equation

$$d \operatorname{Evol}_{s,t}(x) = \sum_{i=1}^{d} V_i(\operatorname{Evol}_{s,t}(x)) du^i(t)$$

then for any smooth function $f:E\to\mathbb{R},$ and every $x\in E$

$$f(\operatorname{Evol}_{s,t}(x)) = \\ = \sum_{k=0}^{M} \sum_{i_1,\dots,u_k=1}^{d} V_{i_1} \cdots V_{i_k} f(x) \int_{s \le t_1 \le \dots \le t_k \le t} du^{i_1}(t_1) \cdots du^{i_k}(t_k) + \\ + R_M(s, t, f)$$

Taylor expansion

with remainder term

$$R_{M}(s,t,f) = \\ = \sum_{i_{0},\dots,u_{M}=1}^{d} \int_{s \leq t_{1} \leq \dots \leq t_{M+1} \leq t} V_{i_{0}} \cdots V_{i_{k}} f(\text{Evol}_{s,t_{0}}(x)) du^{i_{0}}(t_{0}) \cdots du^{i_{k}}(t_{M})$$

holds true for all times $s \leq t$ and every natural number $M \geq 0$.

A lot of work has been done to understand the analysis, algebra and geometry of this expansion (Kua-Tsai Chen, Gerard Ben-Arous, Terry Lyons). It is a starting point of *rough path analysis* (Terry Lyons, Peter Friz, etc).

Hopf algebraic interpretation

Definition

Consider the free algebra \mathbb{A}_d of formal series generated by d non-commutative indeterminates e_1, \ldots, e_d (actually a Hopf Algebra). A typical element $a \in \mathbb{A}_d$ is written as

$$a = \sum_{k=0}^{\infty} \sum_{i_1,\ldots,i_k=1}^d a_{i_1\ldots i_k} e_{i_1} \cdots e_{i_k},$$

sums and products are defined in the natural way. We consider the complete locally convex topology making all projections $a \mapsto a_{i_1...i_k}$ continuous on \mathbb{A}_d , hence a convenient vector space.

Vector fields in \mathbb{A}_d

Definition

We define on \mathbb{A}_d smooth vector fields

 $a \mapsto ae_i$

for i = 1, ..., d.

Signature

Theorem

Let u be a smooth control, then the controlled differential equation

$$d\operatorname{Sig}_{s,t}(a) = \sum_{i=1}^{d} \operatorname{Sig}_{s,t}(a) e_i du^i(t), \ \operatorname{Sig}_{s,s}(a) = a \tag{1}$$

has a unique smooth evolution operator, called signature of u and denoted by Sig, given by

$$\operatorname{Sig}_{s,t}(a) = a \sum_{k=0}^{\infty} \sum_{i_1, \dots, u_k=1}^{d} \int_{s \le t_1 \le \dots \le t_k \le t} du^{i_1}(t_1) \cdots du^{i_k}(t_k) \ e_{i_1} \cdots e_{i_k} \ . \ (2)$$

Actually Sig(e) takes values in a Lie group G and any element of G can be reached up to arbitrary order of accuracy by such evolutions starting at e. Additionally the restriction of linear maps on G is an algebra.

Signature as abstract reservoir

Theorem (Signature is a reservoir)

Let Evol be a smooth evolution operator on a convenient vector space E which satisfies (again the time derivative is taken with respect to the forward variable t) a controlled ordinary differential equation

$$d \operatorname{Evol}_{s,t}(x) = \sum_{i=1}^{d} V_i(\operatorname{Evol}_{s,t}(x)) du^i(t).$$

Then for any smooth (test) function $f : E \to \mathbb{R}$ and for every $M \ge 0$ there is a time-homogenous linear $W = W(V_1, \ldots, V_d, f, M, x)$ from \mathbb{A}_d^M to the real numbers \mathbb{R} such that

$$fig(\operatorname{\mathsf{Evol}}_{s,t}(x)ig) = Wig(\pi_{\mathcal{M}}(\operatorname{\mathsf{Sig}}_{s,t}(1))ig) + \mathcal{O}ig((t-s)^{\mathcal{M}+1}ig)$$

for $s \leq t$.

- This explains that any solution can be represented up to a linear readout – by a universal reservoir, namely signature. Similar constructions can be done in regularity structures, too (branched rough paths, etc).
- This is used in many instances of provable machine learning by, e.g., groups in Oxford (Harald Oberhauser, Terry Lyons, etc), and also ...
- ... at JP Morgan, in particular great recent work on 'Nonparametric pricing and hedging of exotic derivatives' by Terry Lyons, Sina Nejad and Imanol Perez Arribas.
- in contrast to reservoir computing: signature is high dimensional (i.e. infinite dimensional) and a precisely defined, non-random object.
- Can we approximate signature by a lower dimensional random object with similar properties?

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We shall consider now $\mathbb{R}_{\geq 0}$ as time interval except otherwise mentioned. The stochastic basis satisfies usual conditions.

Let us introduce some notation: we denote by $\mathbb S$ the set of simple predictable processes, i.e. for $\omega\in\Omega,\,s\in\mathcal T$

$$H_{s}(\omega) = H_{0}(\omega)\mathbb{1}_{\{0\}}(s) + \sum_{i=1}^{n} H_{i}(\omega)\mathbb{1}_{]\mathcal{T}_{i}(\omega), \mathcal{T}_{i+1}(\omega)]}(s)$$

for an increasing, finite sequence of stopping times $0 = T_0 \leq T_1 \leq \ldots T_{n+1} < \infty$ and H_i being \mathcal{F}_{T_i} measurable, by \mathbb{L} the set of adapted, caglad processes and by \mathbb{D} the set of adapted, cadlag processes on $\mathbb{R}_{\geq 0}$.

These vector spaces are endowed with the metric

$$d(X,Y):=\sum_{n\geq 0}\frac{1}{2^n}E\big[|(X-Y)|_n^*\wedge 1\big],$$

which makes \mathbb{L} and \mathbb{D} complete topological vector spaces. We call this topology the ucp-topology ("uniform convergence on compacts in probability"). Notice that predictable strategies as well as integrators are considered \mathbb{R} valued here, which, however, *contains* the \mathbb{R}^n case.

Good integrators

Definition

An adapted, cadlag process X is called good integrator if the map

 $J_X:\mathbb{S}\to\mathbb{D}$

with

$$(H \bullet X)_t := J_X(H)_t := H_0 X_0 + \sum_{i=1}^n H_i (X_{T_{i+1} \wedge t} - X_{T_i \wedge t}),$$

for $H \in S$, is continuous with respect to the ucp-topologies on the respective spaces (this can even be weakened).

X is a good integrator if and only if X = M + A, where M is a local martingale and A is a process of finite total variation, i.e. X is a semimartingale.

The Emery topology

The Emery topology on the set of semimartingales $\mathbb{S}\mathbb{E}\mathbb{M}$ is defined by the metric

$$d_E(S_1,S_2):=\sum_{n\geq 0}\frac{1}{2^n}\sup_{K\in\mathbb{S},\,\left\|K\right\|_\infty\leq 1}E\big[\left|\left(K\bullet(S_1-S_2)\right)\right|_n^*\wedge 1\big]\,.$$

We can by means of the Bichteler-Dellacherie theorem easily prove the following important theorem.

Theorem

The set of semi-martingales \mathbb{SEM} is a topological vector space and complete with respect to the Emery topology.

Theorem

For every semi-martingale X the map J_X from the space \mathbb{L} of càglàd processes to SEM of semi-martingales is continuous.

lto's formula

We are now already able to formulate and prove Ito's formula in all generality:

Theorem

Let X^1, \ldots, X^n be good integrators and $f : \mathbb{R}^n \to \mathbb{R}$ a C^2 function, then for $t \ge 0$

$$f(X_t) = \sum_{i=1}^n (\partial_i f(X_-) \bullet X^i)_t + \frac{1}{2} \sum_{i,j=1}^n (\partial_{ij}^2 f(X_-) \bullet [X^i, X^j])_t + \sum_{0 \le s \le t} \{f(X_s) - f(X_s)_- - \sum_{i=1}^n \partial_i f(X_s)_- \Delta X_s^i - \frac{1}{2} \sum_{i,j=1}^n \partial_{ij}^2 f(X_s)_- \Delta X_s^i \Delta X_s^j\}$$

(we apply $X_{0-} = 0$ here.)

Semimartingale Signature (existence)

Theorem

Let X^1, \ldots, X^n be good integrators. Consider a free algebra \mathbb{A}^d of power series generated by (non-commutative) generators $e_0, e_i, e_{ij}, e_{ijk}, \ldots$, for $i \leq j \leq k \leq \ldots \in \{1, \ldots, d\}$, then semimartingale signature

sem-Sig = 1 +
$$\int_{0}^{\cdot} (\text{sem-Sig}_{s} ds) e_{0} + \sum_{i=1}^{d} (\text{sem-Sig}_{-} \bullet X^{i}) e_{i} +$$

+ $\sum_{i \leq j=1}^{d} (\text{sem-Sig}_{-} \bullet [X^{i}, X^{j}]) e_{ij} +$
 $\sum_{i \leq j \leq k} (\sum_{s \leq \cdot} \text{sem-Sig}_{s-} \Delta X^{i}_{s} \Delta X^{j}_{s} \Delta X^{k}_{s}) e_{ijk} + \dots$

is a well defined \mathbb{A}^d valued process.

Semi-martingale Signature (density)

The set of all $\langle \ell, \text{sem-Sig} \rangle$ for $\ell \in (\mathbb{A}^d)^*$ is an algebra of semimartingales.

Proof

- The first assertion follows by constructing solutions for finite dimensional (nilpotent of degree *M*) cut off systems.
- By Ito's formula one sees that every polynomial in time and X¹,...,X^d can be precisely written as a finite linear combination of components of the semimartingale signature.
- By Ito's formula one can see that products of components of semimartingale signature can be written as finite linear combinations of components of semimartingale signature.
- Also every integral with integrand $f(., X^1, ..., X^d)$ with respect to a component of semimartingale signature can be written as a finite linear combination of components of signature.
- Therefore the span of the components of semimartingale signature constitutes an algebra.

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