Malliavin Calculus: The Hörmander Theorem

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Basic assumptions on vector fields

We shall always assume the following conditions on vector fields $X : \mathbb{R}^M \times \mathbb{R}^N \to \mathbb{R}^N$:

- 1. X are measurable.
- 2. There is a constant C such that $||X(y, x_1) X(y, x_2)|| \le C||x_1 x_2||$ for all $x_1, x_2 \in \mathbb{R}^N$ and all $y \in \mathbb{R}^M$.
- 3. The function ||X(y,x)|| is bounded by a constant polynomial in ||y|| for all $x \in \mathbb{R}^N$.

Main E&U theorem

Let T > 0 and given a probability space (Ω, \mathcal{F}, P) together with a *d*-dimensional Brownian motion $(W_t)_{0 \le t \le T}$. Let $A, A_1, ..., A_d$ be vector fields satisfying the above conditions and assume that there are a continuous, adapted \mathbb{R}^M -valued process $(Z_t)_{t>0}$ with

$$\sup_{\in [0,T]} ||Z_t||_p < \infty$$

for all $p \geq 2$ and a continuous adapted \mathbb{R}^N -valued process $(\alpha_t)_{t \geq 0}$ with

$$\sup_{\in [0,T]} ||\alpha_t||_q < \infty$$

for some $q \ge 2$, then the stochastic differential equation

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$$X_t = \alpha_t + \int_0^t A(Z_s, X_s) ds + \sum_{i=1}^d \int_0^t A_i(Z_s, X_s) dW_s^i$$

Main E&U theorem

has a unique continuous adapted solution $(X_t)_{0 \le t \le T}$ with

 $\sup_{t\in[0,T]}||X_t||_q<\infty.$

Furthermore the solution can be constructed as L^q -limit of the iteration scheme

$$X_t^{n+1} = \alpha_t + \int_0^t A(Z_s, X_s^n) ds + \sum_{i=1}^d \int_0^t A_i(Z_s, X_s^n) dW_s^i$$
$$X_t^0 = \alpha_t$$

for $0 \leq t \leq T$.

This fundamental result leads to the following observations: given a probability space (Ω, \mathcal{F}, P) together with a *d*-dimensional Brownian motion $(W_t)_{0 \le t \le T}$ in its natural filtration, we can ask whether the solution of the stochastic differential equation

$$dX_t^x = V(X_t^x)dt + \sum_{i=1}^d V_i(X_t^x)dW_t^i$$
$$X_0^x = x$$

for $x \in \mathbb{R}^N$ lies in $\mathcal{D}^{1,2}(\Omega; \mathbb{R}^N)$. Here we work with the isonormal Gaussian process $W : L^2([0, T], \mathbb{R}^d) \to L^2(\Omega)$

$$W(h) = \sum_{i=1}^d \int_0^T h_i(s) dW_s^i.$$

C^{∞} -boundedness

We assume the following conditions on the vector fields $V, V_1, ..., V_d : \mathbb{R}^N \to \mathbb{R}^N$:

- 1. The vector fields are smooth.
- 2. All derivatives of order higher than 1 are bounded.

These conditions are usually referred to as C^{∞} -boundedness conditions.

Malliavin derivative of X_t

Let $V, V_1, ..., V_d : \mathbb{R}^N \to \mathbb{R}^N$ be vector fields satisfying C^{∞} -boundedness conditions, then $X_t^{\times} \in \mathcal{D}^{\infty} := \bigcap_{p \ge 1, k \ge 1} \mathcal{D}^{k,p}$ for $0 \le t \le T$. The first Malliavin derivative satisfies the following stochastic differential equation

$$D_{r}^{k}X_{t}^{x} = V_{k}(X_{r}^{x}) + \int_{r}^{t} dV(X_{s}^{x})D_{r}^{k}X_{s}^{x}ds + \sum_{i=1}^{d}\int_{r}^{t} dV_{i}(X_{s}^{x})D_{r}^{k}X_{s}^{x}dW_{s}^{i}$$

for $0 \leq r \leq t \leq T$.

For the proof we apply two observations. Given $u \in \mathcal{D}^{1,2}(\Omega; \mathbb{R}^N) \otimes H$ predictable, then for $t \geq r$

$$D_r \int_0^t u_s ds = \int_r^t D_r u_s ds$$

by Riemannian approximations and closedness of the operator, since $D_r u_s = 0$ almost surely if r > s.

Given predictable $u = (u_1, ..., u_d) \in \mathcal{D}^{1,2}(\Omega; \mathbb{R}^N) \otimes H$, then for $t \ge r$

$$D_r^k \int_0^t \sum_{i=1}^d u_i(s) dW_s^i = \int_r^t \sum_{i=1}^d D_r^k u_i(s) dW_s^i + u_k(r),$$

again by Riemannian sums and closedness of the Malliavin derivative operator.

Going to the Picard approximation scheme we can apply these results to obtain a sequence $X_t^n \in L^{\infty-0}$ with $X^n \in \mathcal{D}^{1,p}$ for $p \ge 2$ by induction and the chain rule for $n \ge 0$.

The derivatives converge to the solution of a stochastic differential equation, so we conclude by closedness. The solution of this stochastic differential equation exist due to the previous E&U theorem. For higher derivatives we proceed by induction.

Semi-martingale notations

We are working with Ito diffusions, i.e. continuous adapted processes X_t of the form

$$X_t = X_0 + \int_0^t v(s) ds + \sum_{i=1}^d \int_0^t u_i(s) dW_s^i,$$

where we assume all processes in question to be predictable and satisfy some square integrability assumptions. Notice that this decomposition into a finite variation process and a martingale is unique. For two Ito processes X and Y the quadratic variation process $(\langle X, Y \rangle_t)_{0 \le t \le T}$ is a continuous, adapted process given by

$$\langle X, Y \rangle_t = \int_0^t (\sum_{i=1}^d u_i^X(s)(u_i^Y(s))^\mathsf{T}) ds.$$

Semi-martingale notations

The Stratonovich integral (in the one-dimensional case) is then defined by

$$\int_0^t X_s \circ dY_s := \int_0^t X_t dY_s + \frac{1}{2} \langle X, Y \rangle_t.$$

We can therefore write by Ito's formula for Ito diffusions

$$df(X_t) = (df)(X_t)dX_t + \frac{1}{2}(d^2f)(X_t)(dX_t)(dX_t) \\ = (df)(X_t) \circ dX_t.$$

Semi-martingale notations

Consequently the Stratonovich calculus is of first order, however, we can only integrate continuous semi-martingales. Given the solution of our SDE, we can transform since integrands are semi-martingales to Stratonovich notation and obtain

$$dX_t^{\times} = V_0(X_t^{\times})dt + \sum_{i=1}^d V_i(X_t^{\times}) \circ dW_t^i,$$

with the Stratonovich drift.

In order to find a good representation of the Malliavin derivative, we introduce first variations of the solution of the stochastic differential equation:

$$dJ_{s \to t}(x) = dV_0(X_t^x) \cdot J_{s \to t}(x)dt + \sum_{i=1}^d dV_i(X_t^x) \cdot J_{s \to t}(x) \circ dW_t^i,$$
$$J_{s \to s}(x) = id_N,$$

for $t \geq s$.

A similar equation is satisfied by the Malliavin derivative itself (except for the initial value!). The equation for the inverse is of the same type, namely

$$d(J_{s \to t}(x))^{-1} = -J_{s \to t}(x)^{-1} \cdot dV_0(X_t^x)dt -$$

 $-\sum_{i=1}^d J_{s \to t}(x)^{-1} \cdot dV_i(X_t^x) \circ dW_t^i.$

Calculating the semi-martingale decomposition of $(J_{0\to t}(x))^{-1}J_{0\to t}(x)$ yields the result, namely

$$(J_{0\to t}(x))^{-1}J_{0\to t}(x) = id_N,$$

hence the statement on invertibility is justified.

Furthermore, we are able to write the Malliavin derivative,

$$D_s^i X_t^x = J_{0 \to t}(x) J_{0 \to s}(x)^{-1} V_i(X_s^x) \mathbb{1}_{[0,t]}(s).$$

This is due to the fact that the $\mathbb{R}^N\text{-valued}$ solution process $(Y_t)_{r\leq t\leq \mathcal{T}}$ of

$$Y_t = V_k(X_r^x) + \int_r^t dV(X_s^x) Y_s ds + \sum_{i=1}^d \int_r^t dV_i(X_s^x) Y_s dW_s^i,$$

is given through

$$Y_t = J_{0 \to t}(x) J_{0 \to r}(x)^{-1} V_k(X_r^x)$$

for $r \leq t$.

Malliavin Covariance Matrix

We give ourselves a scalar product on \mathbb{R}^N , then we can calculate the covariance matrix with respect to a orthonormal basis, i.e.

$$\langle \gamma(X_t^{\times})\xi,\xi\rangle := \sum_{i=1}^d \int_0^t \left\langle J_{0\to t}(x)J_{0\to s}(x)^{-1}V_i(X_s^{\times}),\xi\right\rangle^2 ds.$$

Consequently, the covariance matrix can be calculated via the reduced covariance matrix

$$\langle C_t \xi, \xi \rangle := \sum_{i=1}^d \int_0^t \left\langle J_{0 \to s}(x)^{-1} V_i(X_s^x), \xi \right\rangle^2 ds,$$

$$\gamma(X_t^x) = J_{0 \to t}(x) C^t J_{0 \to t}(x)^{\mathsf{T}}.$$

In order to show invertibility of $\gamma(X_t^{\times})$ it is hence sufficient to show it for C_t , since the first variation process $J_{0 \to t}(x)$ is invertible.

Uniform Hörmander Assumptions

$$\langle V_1(x),\ldots,V_d(x),[V_i,V_k](x)(i,k=0,\ldots,d),\ldots\rangle = \mathbb{R}^N$$

for all $x \in \mathbb{R}^N$ in a uniform way, i.e. there exists a finite number of vector fields X_1, \ldots, X_N generated by the above procedure through Lie-bracketing and c > 0 such that

$$\inf_{\xi\in \mathcal{S}^{N-1}}\sum_{k=1}^N \langle X_k(x),\xi
angle^2\geq c$$

for all $x \in \mathbb{R}^N$. Here we apply again the Stratonovich drift vector field, i.e.

$$V_0(x) := V(x) - \frac{1}{2} \sum_{i=1}^d DV_i(x) \cdot V_i(x).$$

Main Theorem (Malliavin)

Let $(\Omega, \mathcal{F}, P, (\mathcal{F}_t)_{t\geq 0})$ be a filtered probability space and let $(W_t)_{t\geq 0}$ be a *d*-dimensional Brownian motion adapted to the filtration (which is not necessarily generated by the Brownian motion). Let V, V_1, \ldots, V_d , the diffusion vector fields be C^{∞} -bounded on \mathbb{R}^N and consider the solution $(X_t^{\times})_{0\leq t\leq T}$ of a stochastic differential equation (in Stratonovich notation). V_0 denotes the Stratonovich corrected drift term,

$$dX_t^{\times} = V_0(X_t^{\times})dt + \sum_{i=1}^d V_i(X_t^{\times}) \circ dW_t^i,$$
$$X_0^{\times} = x.$$

Main Theorem (Malliavin)

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Assume uniform Hörmander condition. Then for any $p \ge 1$ we find numbers $\epsilon_0(p) > 0$ and an integer $K(p) \ge 1$ such that for each 0 < s < T

$$\sup_{\in S^{N-1}} P(\langle C^s \xi, \xi \rangle < \epsilon) \le \epsilon^p$$

holds true for $0 \le \epsilon \le s^{\mathcal{K}(p)} \epsilon_0(p)$. The result holds uniformly in x.

The last statement implies that $\frac{1}{\det(\gamma(X_t^{\times}))} \in L^{\infty-0}$ and hence due to the fact that $X_t^{\times} \in \mathcal{D}^{\infty}$ for t > 0 the law of X_t^{\times} has a density with respect to the Lebesgue measure, which is Schwarz.

Take t > 0. We have to form the Malliavin covariance matrix γ_t , which is done by well-known formulas on the first variation. The covariance matrix can be decomposed into

$$\gamma(X_t^{\mathsf{X}}) = J_{0 \to t}(\mathsf{X})C_t J_{0 \to t}(\mathsf{X})^{\mathsf{T}},$$

where C_t , the reduced covariance matrix, is defined via

$$\langle y, C_t y \rangle = \sum_{p=1}^d \int_0^t \langle y, J_{0 \to s}(x)^{-1} \cdot V_p(X_s^x) \rangle^2 ds.$$

We first show that C_t is a positive operator. We denote the kernel of C_t by $K_t \subset \mathbb{R}^N$ and get a decreasing sequence of closed random subspaces of \mathbb{R}^N . $V = \bigcup_{t>0} K_t$ is a deterministic subspace by the Blumenthal zero-one law, i.e. there exists a null set N such that Vis deterministic on N^c . We shall do the following calculus on N^c .

We fix $y \in V$, then we consider the stopping time

$$\theta := \inf\{s, q_s > 0\}$$

with respect to the continuous semi-martingale

$$q_s = \sum_{p=1}^d \left\langle y, J_{0\to s}(x)^{-1} \cdot V_p(X_s^{\times}) \right\rangle^2,$$

Then $\theta > 0$ almost surely and $q_{s \wedge \theta} = 0$ for $s \geq 0$.

Now, a continuous L^2 -semi-martingale with values in $\mathbb R$

$$M_s - M_0 = \sum_{k=1}^d \int_0^s \alpha_k(u) dW_u^k + \int_0^s \beta(u) du$$

for $s \ge 0$, which vanishes up to the stopping time θ , satisfies – due to the Doob-Meyer decomposition –

$$\alpha_k(\boldsymbol{s}\wedge\boldsymbol{\theta})=\boldsymbol{0}$$

for $k = 1, \ldots, d$, and $\beta(s \wedge \theta) = 0$, for $s \ge 0$.

We shall apply this consideration for the continuous semi-martingales $m_s := \langle y, J_{0 \to s}(x)^{-1} \cdot V_p(X_s^{\times}) \rangle$ on [0, t] for $p = 1, \ldots, d$. Therefore we need to calculate the Doob-Meyer decomposition of $(m_s)_{0 < s < t}$.

$$\begin{split} dm_s &= -\left\langle y, J_{0 \to s}(x)^{-1} dV_0(X_s^x) V_p(X_s^x) \right\rangle ds - \\ &- \sum_{i=1}^d \left\langle y, J_{0 \to s}(x)^{-1} dV_i(X_s^x) V_p(X_s^x) \right\rangle \circ dW_s^i + \\ &+ \left\langle y, J_{0 \to s}(x)^{-1} dV_p(X_s^x) \cdot V_0(X_s^x) \right\rangle ds + \\ &+ \sum_{i=1}^d \left\langle y, J_{0 \to s}(x)^{-1} dV_p(X_s^x) \cdot V_i(X_s^x) \right\rangle \circ dW_s^i \\ &= \left\langle y, J_{0 \to s}(x)^{-1} [V_p, V_0](X_s^x) \right\rangle ds + \\ &+ \sum_{i=1}^d \left\langle y, J_{0 \to s}(x)^{-1} [V_p, V_i](X_s^x) \right\rangle \circ dW_s^i \,, \end{split}$$

where we denote by d the stochastic differential of m and the first derivative of V_i .

From the Doob-Meyer decomposition this leads to

$$ig\langle y, J_{0
ightarrow s}(x)^{-1} \cdot [V_p, V_i](X_s^x) ig
angle = 0 \ ig\langle y, J_{0
ightarrow s}(x)^{-1} \cdot [V_p, V_0](X_s^x) ig
angle = 0$$

for $i = 1, \ldots, d$, $p = 1, \ldots, d$ and $0 \le s \le \theta$.

Consequently the above equation leads by iterative application to

$$\langle y, J_{0 \to s}(x)^{-1} \cdot \mathcal{D}(X_s^x) \rangle = 0$$

for $s \leq \theta$, where $\mathcal{D}(x)$ is the set of Lie brackets at x. Evaluation at s = 0 yields y = 0, since $\mathcal{D}(x)$ spans \mathbb{R}^N , hence C_t is invertible.

Therefore we obtain that there is a null set N, such that on N^c the matrix C_t has an empty kernel. Hence the law is absolutely continuous with respect to Lebesgue measure, since $J_{0\to t}(x)$ is invertible and therefore γ_t has vanishing kernel.

Smoothness – Step 1

Consider the random quadratic form

$$\langle C_s \xi, \xi \rangle = \sum_{i=1}^d \int_0^s \left\langle J_{0 \to u}(x)^{-1} V_i(X_u^x), \xi \right\rangle^2 du.$$

We define

$$\begin{split} \Sigma_0' &:= \{V_1, \dots, V_d\} \\ \Sigma_n' &:= \{[V_k, V], k = 1, \dots, d, V \in \Sigma_{n-1}'; [V_0, V] + \\ &+ \frac{1}{2} \sum_{i=1}^d [V_i, [V_i, V]], V \in \Sigma_{n-1}' \} \end{split}$$

for $n \geq 1$.

Then we know that there exists j_0 such that

$$\inf_{\xi\in\mathcal{S}^{M-1}}\sum_{j=0}^{j_0}\sum_{V\in\Sigma_j'}\left\langle V(x),\xi
ight
angle^2\geq c$$

uniformly in $x \in \mathbb{R}^M$.

Smoothness – Step 2

We define $m(j) := 2^{-4j}$ for $0 \le j \le j_0$ and the sets

$$E_j := \{\sum_{V \in \Sigma'_j} \int_0^s \left\langle J_{0 \to u}(x)^{-1} V(X^x_u), \xi \right\rangle^2 du \le \epsilon^{m(j)} \}.$$

We consider the decomposition

 $E_0 = \{ \langle C^s \xi, \xi \rangle \leq \epsilon \} \subset (E_0 \cap E_1^c) \cup (E_1 \cap E_2^c) \cup \cdots \cup (E_{j_0-1} \cap E_{j_0}^c) \cup F,$ $F = E_0 \cap \cdots \cap E_{j_0}.$

and proceed with

$$P(F) \leq C \epsilon^{\frac{q\beta}{2}},$$

for $\epsilon \leq \epsilon_1$. Furthermore $0 < \beta < m(j_0)$, any $q \geq 2$, a constant C depending on q and the norms of the derivatives of the vector fields V_0, \ldots, V_d . The number ϵ_1 is determined by the following two (!) equations

Smoothness – Step 3

We obtain furthermore with $n(j) = \#\Sigma'_j$

$$\begin{split} & P(E_j \cap E_{j+1}^c) \\ \leq \sum_{V \in \Sigma_j'} P\left(\int_0^s \left\langle J_{0 \to u}(x)^{-1} V(X_u^x), \xi \right\rangle^2 du \leq \epsilon^{m(j)}, \\ & \sum_{k=1}^d \int_0^s \left\langle J_{0 \to u}(x)^{-1} [V_k, V](X_u^x), \xi \right\rangle^2 du + \\ & + \int_0^s \left\langle J_{0 \to u}(x)^{-1} \left([V_0, V] + \frac{1}{2} \sum_{i=1}^d [V_i, [V_i, V]] \right) (X_u^x), \xi \right\rangle^2 du \\ & > \frac{\epsilon^{m(j+1)}}{n(j)} \right), \end{split}$$

Since we can find the bounded variation and the quadratic variation part of the martingale $(\langle J_{0\to u}(x)^{-1}V(X_u^x), \xi \rangle)_{0 \le u \le s}$ in the above expression, we are able to apply Norris' Lemma. We observe that 8m(j+1) < m(j), hence we can apply it with $q = \frac{m(j)}{m(j+1)}$.

Smoothness – Step 4

We obtain for $p \ge 2 - \text{still}$ by the Norris' Lemma – the estimate

$$P(E_j \cap E_{j+1}^c) \leq d_1 \left(\frac{\epsilon^{m(j+1)}}{n(j)}\right)^{rp} + d_2 \exp\left(-\left(\frac{\epsilon^{m(j+1)}}{n(j)}\right)^{-\nu}\right)$$

for $\epsilon \leq \epsilon_2$. Furthermore $r, \nu > 0$ with $18r + 9\nu < q - 8$, the numbers d_1, d_2 depend on the vector fields V_0, \ldots, V_d , and on p, T. The number ϵ_2 can be chosen like $\epsilon_2 = \epsilon_3 s^{k_1}$, where ϵ_3 does not depend on s anymore.

Smoothness – Step 5

Putting all together we take the minimum of ϵ_1 and ϵ_2 to obtain the desired dependence on *s* by applying the following lemma:

Given a random matrix $\gamma \in \bigcap_{p \ge 1} L^p(\Omega)$ and assume that for $p \ge 1$ there is $\epsilon_0(p)$ such that

$$\sup_{\xi\in S^{M-1}} P(\langle \gamma\xi,\xi\rangle<\epsilon) \le \epsilon^p$$

for $0 \leq \epsilon \leq \epsilon_0(p)$, then $\frac{1}{\det(\gamma)} \in \cap_{p \geq 1} L^p(\Omega)$.

Definition

Let $(X_t^x)_{t\geq 0}$ denote the solution of our SDE and assume the uniform Hörmander condition. Fix t > 0 and $x \in \mathbb{R}^N$. Fix a direction $v \in \mathbb{R}^N$. We define a set of Skorohod-integrable processes

$$\mathbb{A}_{t,x,v} = \{a \in \mathsf{dom}(\delta) \text{ such that } \sum_{i=1}^d \int_0^t J_{0 \to s}(x)^{-1} V_i(X_s^x) a_s^i ds = v\}.$$

Let $(X_t^x)_{t\geq 0}$ denote the unique solution of our SDE and assume d = N. Fix t > 0 and $x \in \mathbb{R}^N$. Assume furthermore uniform ellipticity, i.e., there is c > 0 such that

$$\inf_{\xi\in S^{M-1}}\sum_{k=1}^N \langle V_k(x),\xi\rangle^2 \geq c.$$

Then $\mathbb{A}_{t,x,v} \neq \emptyset$ and there exists a real valued random variable π (which depends linearly on v) such that for all bounded random variables f we obtain

$$\left.\frac{d}{d\epsilon}\right|_{\epsilon=0} E(f(X_t^{x+\epsilon v})) = E(f(X_t^x)\pi).$$

Here the proof is particularly simple, since we can take a matrix $\sigma(x) := (V_1(x), \ldots, V_N(x))$, which is uniformly invertible with bounded inverse. We define

$$\mathsf{a}_{\mathsf{s}} := rac{1}{t} \sigma(\mathsf{X}^{ imes}_{\mathsf{s}})^{-1} \cdot \mathsf{J}_{0 o \mathsf{s}}(\mathsf{x}) \mathsf{v}$$

for $0 \le s \le t$ and obtain that $a \in \mathbb{A}_{t,x,v}$. Furthermore

$$\pi = \sum_{i=1}^d \int_0^t a_s^i dW_s^i,$$

since the Skorohod integrable process *a* is in fact adapted, continuous and hence Ito-integrable.

Let $(X_t^x)_{t\geq 0}$ denote the unique solution of our SDE and assume uniform Hörmander condition. Fix t > 0 and $x \in \mathbb{R}^N$. Fix a direction $v \in \mathbb{R}^N$. Then $\mathbb{A}_{t,x,v} \neq \emptyset$ and there exists a real valued random variable π (which depends linearly on v) such that for all bounded random variables f we obtain

$$\left.\frac{d}{d\epsilon}\right|_{\epsilon=0} E(f(X_t^{x+\epsilon v})) = E(f(X_t^x)\pi).$$

We can choose π to be the Skorohod integral of any element $a \in \mathbb{A}_{t,x,v} \neq \emptyset$.

We take f bounded with bounded first derivative, then we obtain

$$\frac{d}{d\epsilon}\Big|_{\epsilon=0} E(f(X_t^{x+\epsilon v})) = E(df(X_t^x)J_{0\to t}(x)\cdot v).$$

If there is $a \in \mathbb{A}_{t,x,v}$, we obtain

$$E(df(X_t^{x})J_{0\to t}(x)\cdot v)$$

= $E(df(X_t^{x})\sum_{i=1}^{d}\int_{0}^{t}J_{0\to t}(x)J_{0\to s}(x)^{-1}V_i(X_s^{x})a_s^ids)$
= $E(\sum_{i=1}^{d}\int_{0}^{t}df(X_t^{x})J_{0\to t}(x)J_{0\to s}(x)^{-1}V_i(X_s^{x})a_s^ids)$
= $E(\sum_{i=1}^{d}\int_{0}^{t}D_s^if(X_t^{x})a_s^ids) = E(f(X_t^{x})\delta(a)).$

Here we cannot assert that the strategy is Ito-integrable, since it will anticipative in general. In order to see that $\mathbb{A}_{t,x,\nu} \neq \emptyset$ we construct an element, namely

$$a_s^i := \left\langle J_{0 \to s}(x)^{-1} V_i(X_s^{\times}), (C^t)^{-1} v \right\rangle,$$

where C^t denotes the reduced covariance matrix.

Indeed

$$\begin{split} &\sum_{i=1}^d \left\langle \int_0^t J_{0\to s}(x)^{-1} V_i(X_s^x) a_s^i ds, \xi \right\rangle \\ &= \sum_{i=1}^d \int_0^t \left\langle J_{0\to s}(x)^{-1} V_i(X_s^x), \xi \right\rangle \left\langle J_{0\to s}(x)^{-1} V_i(X_s^x), (C^t)^{-1} v \right\rangle ds \\ &= \left\langle \xi, C^t(C^t)^{-1} v \right\rangle = \left\langle \xi, v \right\rangle \end{split}$$

for all $\xi \in \mathbb{R}^N$, since C^t is a symmetric random operator defined via

$$\langle \xi, C^t \xi \rangle = \sum_{i=1}^d \int_0^t \langle J_{0 \to s}(x)^{-1} V_i(X_s^x), \xi \rangle^2 ds$$

for $\xi \in \mathbb{R}^N$.

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9